

MATH 2040 A Lecture 9 (Oct 6, 2016)

§ Cayley-Hamilton Theorem (textbook § 5.4)

Recall: Given $T: V \rightarrow V$, ($\dim V < +\infty$)

a subspace $W \subseteq V$ T -invariant $\Leftrightarrow T(W) \subseteq W$

Examples: $\{0\}$, V , $N(T)$, $R(T)$, E_λ

T -cyclic subspace gen. by $\vec{v} \in V$:

$$W = \text{span} \{ \vec{v}, T\vec{v}, T^2\vec{v}, \dots \} \subseteq V$$

e.g. $T(\vec{v} + 2T\vec{v}) = T\vec{v} + 2T^2\vec{v} \in W$

Remember: If W is a T -invariant subspace

\Rightarrow do restriction $T|_W: W \rightarrow W$ linear on W

Lemma: char. poly of $T|_W$ divides char. poly. of T

Example: Consider

$$T: P_3(\mathbb{R}) \longrightarrow P_3(\mathbb{R})$$

$$T(f) = f''$$

Q: $x^3 \in P_3(\mathbb{R}) \Rightarrow$ what is the T -cyclic subspace generated by x^3 ?

$$x^3 \xrightarrow{T} 6x \xrightarrow{T} 0 \xrightarrow{T} 0 \dots\dots$$

$$W = \text{span} \{x^3, 6x\} \quad 2\text{-dim } T\text{-invariant} \subseteq \mathcal{P}_3(\mathbb{R})$$

restriction $\rightsquigarrow T|_W : W \rightarrow W$ on 2-dim vector space

Find char. poly. of $T|_W : \beta_W = \{x^3, x\}$ basis for W

$$[T|_W]_{\beta_W} = \begin{pmatrix} 0 & 0 \\ 6 & 0 \end{pmatrix} \rightsquigarrow f_W(t) = \det \begin{pmatrix} -t & 0 \\ 6 & -t \end{pmatrix} = t^2$$

Find char. poly. of $T : \beta = \{1, x, x^2, x^3\}$

$$[T]_{\beta} = \begin{pmatrix} 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 6 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \rightsquigarrow f(t) = \det(A - tI) = t^4$$

$\underbrace{\hspace{10em}}_A$

Note: $f_W(t) = t^2 \mid t^4 = f(t)$.

Proof of Lemma: Take $\beta_W \subseteq W$ any basis

extend $\rightsquigarrow \beta \subseteq V$ basis

$$\beta = \{ \underbrace{\vec{v}_1, \dots, \vec{v}_k}_{\beta \in W}, \vec{v}_{k+1}, \dots, \vec{v}_n \}$$

$$[T]_{\beta} = \begin{pmatrix} \boxed{k} & & & \\ & \boxed{k} & & \\ & & \bigcirc & \\ & & & \boxed{*} \end{pmatrix}$$

$\uparrow \because W \text{ is } T\text{-inv.}$

\rightsquigarrow compute det.

$$\det \begin{pmatrix} A & B \\ \bigcirc & C \end{pmatrix} = \det(A) \det(C)$$

$$f(t) = \det \begin{pmatrix} \square & -tI & * \\ 0 & \square & * \\ & & \square & -tI \end{pmatrix} = \overbrace{\det(\square - tI)}^{f(t)} \cdot \det(\square - tI)$$

Caution: $\det \begin{pmatrix} A & B \\ D & C \end{pmatrix} \neq \det(A)\det(C) - \det(B)\det(D)$

Cayley-Hamilton Theorem:

Let $T: V \rightarrow V$ be a linear map. If $f(t) = \text{char. poly. of } T$,

$$\Rightarrow f(T) = O_V \text{ "zero transformation."}$$

Note: $f(t) = t^2 + 2t \rightsquigarrow f(T) = T^2 + 2T: V \rightarrow V$ linear.

A matrix example:

$$A = \begin{pmatrix} 1 & 2 \\ -2 & 1 \end{pmatrix} \rightsquigarrow f(t) = \det \begin{pmatrix} 1-t & 2 \\ -2 & 1-t \end{pmatrix} = t^2 - 2t + 5$$

"Plug" A into $f(t)$:

$$f(A) = A^2 - 2A + 5I \quad (= 0 \text{ by Cayley-Hamilton})$$

↑
check by direct calculation

One application: (compute A^{-1})

$$A^2 - 2A + 5I = 0 \Rightarrow A - 2I + 5A^{-1} = 0$$

$\times A^{-1}$

$$\Rightarrow A^{-1} = \frac{1}{5} \underbrace{(-A + 2I)}$$

easier to compute

$$[A \mid I] \xrightarrow{\text{ref}} [I \mid A^{-1}]$$